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Introduction to GPS and PICAXE

Introduction

Welcome to this short tutorial introducing the use of GPS with the popular PICAXE system.

“The **Global Positioning System (GPS)** is a global navigation satellite system (GNSS) developed by the United States Department of Defence and managed by the United States Air Force 50th Space Wing. It is the only fully functional GNSS in the world, can be used freely by anyone, anywhere, and is often used by civilians for navigation purposes. It uses a constellation of between 24 and 32 medium Earth orbit satellites that transmit precise radiowave signals, which allow GPS receivers to determine their current location, the time, and their velocity.”

http://en.wikipedia.org/wiki/Global_Positioning_System

In this tutorial we will be using the EM-410 GPS module manufactured by Globalsat, and a PICAXE 18X chip.

This is also the point where I say that I'm not responsible for the content of the external links provided. People always write this, surly someone is responsible for all the world's "external links". Maybe we will never know who is...

Background Reading

I recommend reading the following articles to build up your knowledge and understanding of GPS' and their interface.

- The sparkfun GPS tutorial:

http://www.sparkfun.com/commerce/tutorial_info.php?tutorials_id=68&page=1

- GPS tutorial by Michael Simpson, part 1 only (this deals more with PC interface of GPS) :

<http://www.kronosrobotics.com/Projects/GPS.shtml>

- NMEA reference guide:

<http://www.sparkfun.com/datasheets/GPS/NMEA%20Reference%20Manual1.pdf>

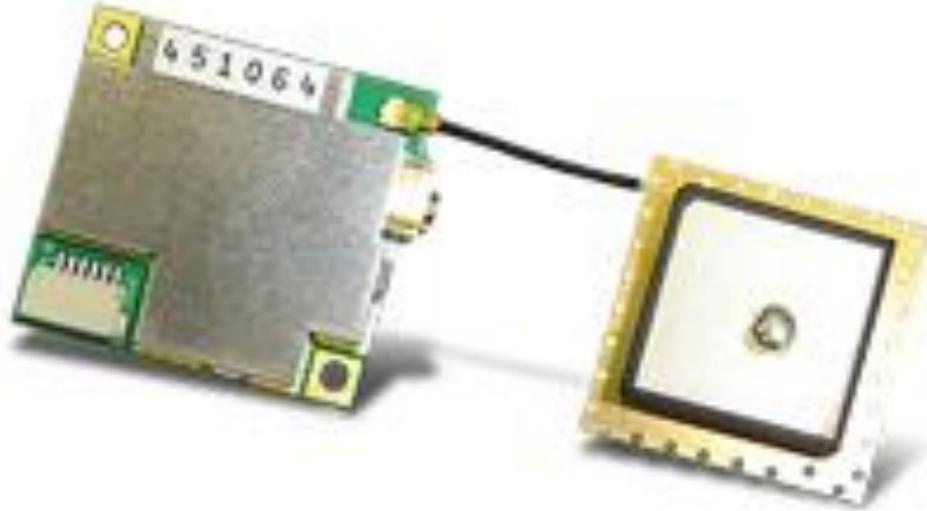
- sparkfun GPS buying guide :

http://www.sparkfun.com/commerce/tutorial_info.php?tutorials_id=127

The EM-410 is not mentioned in any of the GPS guides, however you can consider it to be almost exactly the same as the EM-406.

Once you have a good understanding of GPS, NMEA sentences and have reached a higher plane on enlightenment....continue on.

EM-410



The Em-410 is a very small low cost GPS receiver. It uses an active antenna which can either be a ceramic chip antenna (shown in picture) or one on a wire. The connector is MMCX female on the board. A search for “MMCX” on eBay will give you a host of suitable antennas.

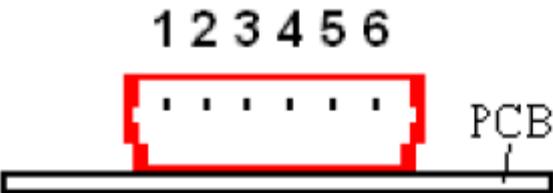
The module uses a rather annoying connector, this can be purchased from cool components or Sparkfun.

EM-410 [Datasheet](#)



Annoying connector

EM-410 Pins



PIN	NAME
PIN 1	VDD
PIN 2	GND
PIN 3	GPS-TX
PIN 4	GPS-RX
PIN 5	GPS-LED
PIN 6	GPS-VBAT

3.3v

0v

To PICAXE input

To PICAXE output

*

3.3v

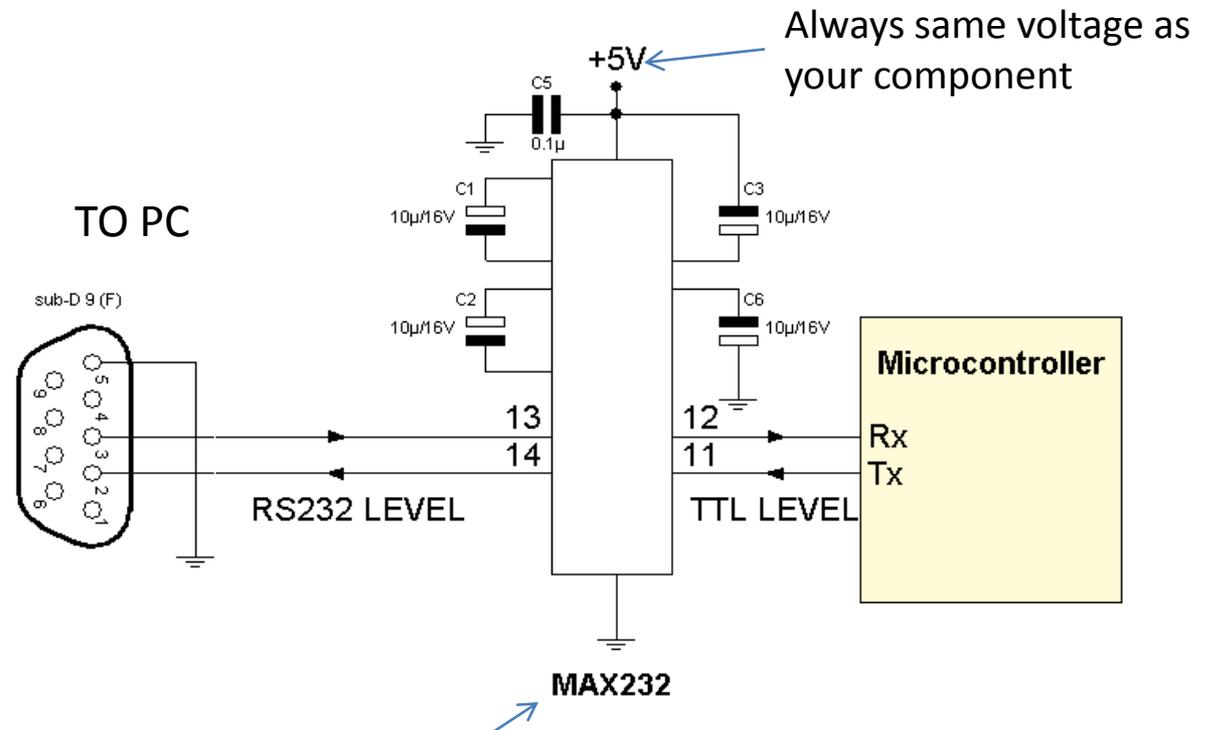
Taken and adapted from EM-410
Datasheet

*I still haven't figured out how
to use this. I'm not risking
putting power into it.

RS-232 Setup

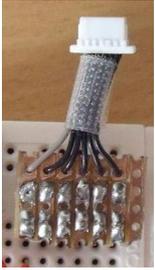
This is if you want to have a direct PC link to first just to check the GPS is working or to see the output on a terminal window.

The RS-232 is a generic set up. All it does is change the voltage level of the input to a higher one. This is because the PC serial signals operate on up to 12v and often electronic components operate on 5v or 3.3v. So all you need to do to use this generic circuit: connect the GPS RX and TX to the chip, and don't forget to change the chip voltage to 3.3v. Connect to your PC serial port, and view the output with a terminal program.

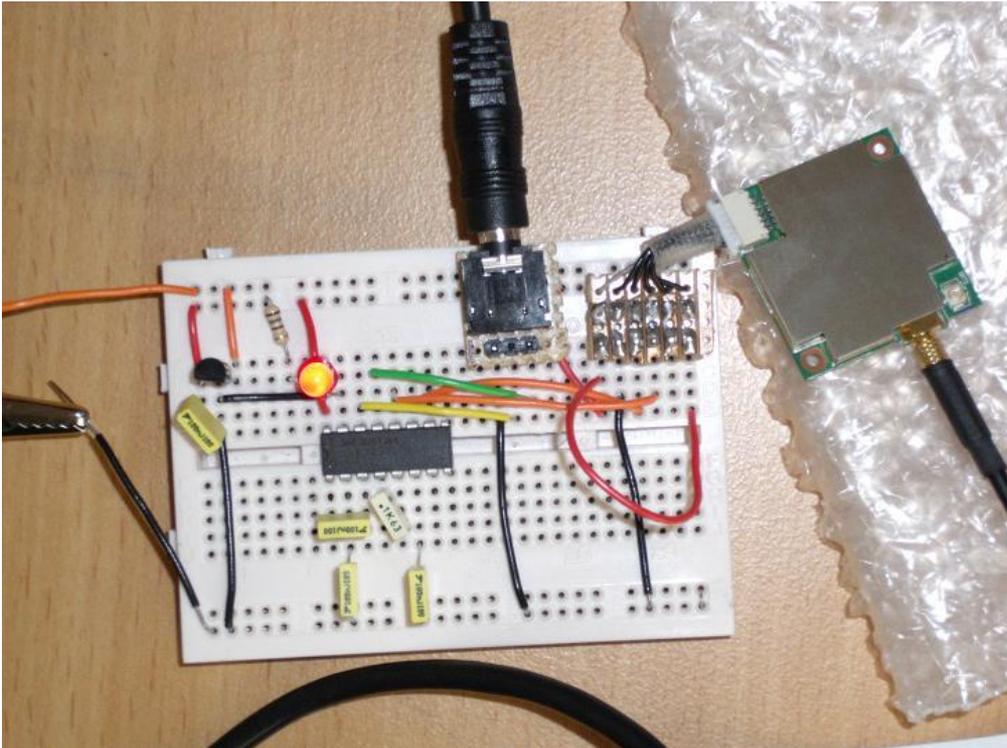


The MAX232 is one of many chips that will do this job.

Setup



This is the annoying connector where the other end has been cut off and the wires have been broken out onto pins which then allow it to be plugged into a breadboard.



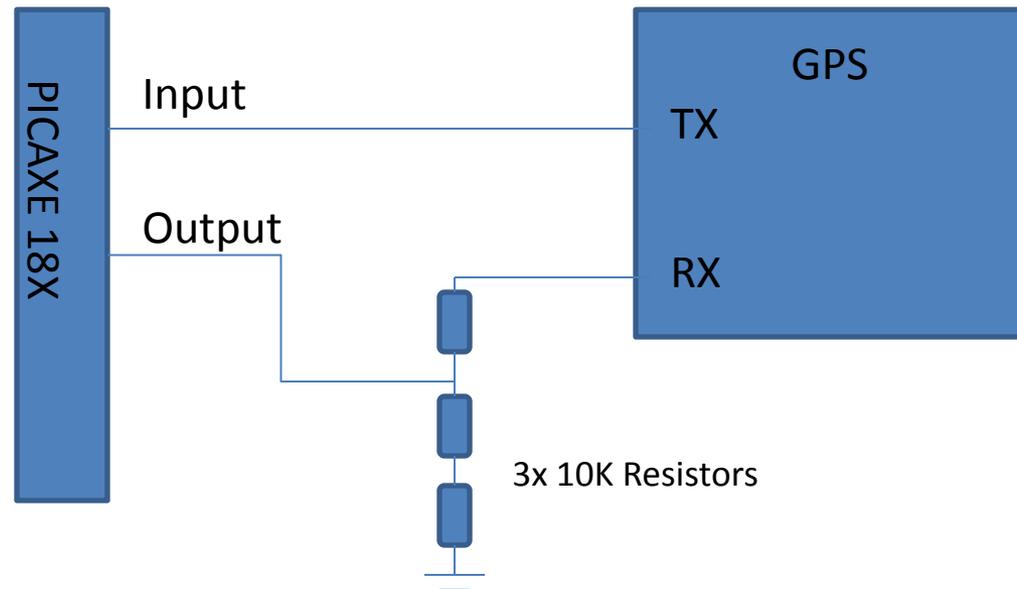
This is a picture of my setup, the GPS is connected to the PC via a RS-232 chip and serial cable.

Setup

Getting the module up and running is easy.

- Power it up according to the datasheet, (note GPS-VBAT must be powered for operation) **GPS module is 3.3V**
- Connect GPS-TX to a PICAXE input
- Connect GPS-RX to a PICAXE output

Once powered the module will immediately begin to output serial data. Check that it is with a logic probe on the GPS-TX pin.



Setup

The screenshot shows the Terminal v1.9b interface with the following settings:

- COM Port: COM8
- Baud rate: 4800
- Data bits: 8
- Parity: none
- Stop bits: 1
- Handshaking: none
- Settings: Auto Dis/Connect, AutoStart Script, Time, CR=LF, Stream log, Stay on Top, custom BR: 9600, Rx Clear: 27, ASCII table, Scripting, Graph, Remote, CTS, CD, DSR, RI.
- Receive: CLEAR, Reset Counter, Counter = 159, HEX/ASCII, Dec/Hex, Bin, StartLog, StopLog, REQ_RES.
- Transmit: CLEAR, Send File, 0, CR=CR+LF, FRAME ERROR, DTR, RTS.
- Macros: Set Macros, M1-M24.
- FF: +CR, Send.
- Connected: Rx: 10484, Tx: 0.

The main window displays the following raw output from the GPS module:

```
$GPGSA,A,3,14,32,27,30,29,09,31,12,,,,,1.6,1.1,1.2*37
$GPRMC,164628.000,A,5256.6625,N,00114.4058,W,0.10,14.11,260609,,A*42
$GPGGA,164629.000,5256.6625,N,00114.4058,W,1.08,1.1,76.1,M,47.5,M,,0000*70
$GPGSA,A,3,14,32,27,30,29,09,31,12,,,,,1.6,1.1,1.2*37
$GPRMC,164629.000,A,5256.6625,N,00114.4058,W,0.09,12.14,260609,,A*48
$GPGGA,164630.000,5256.6625,N,00114.4059,W,1.08,1.1,76.0,M,47.5,M,,0000*78
$GPGSA,A,3,14,32,27,30,29,09,31,12,,,,,1.6,1.1,1.2*37
$GPRMC,164630.000,A,5256.6625,N,00114.4059,W,0.10,16.77,260609,,A*48
$GPGGA,164631.000,5256.6625,N,00114.4059,W,1.08,1.1,75.9,M,47.5,M,,0000*73
$GPGSA,A,3,14,32,27,30,29,09,31,12,,,,,1.6,1.1,1.2*37
$GPRMC,164631.000,A,5256.6625,N,00114.4059,W,0.00,,260609,,A*61
$GPGGA,164632.000,5256.6625,N,00114.4059,W,1.08,1.1,75.9,M,47.5,M,,0000*70
$GPGSA,A,3,14,32,27,30,29,09,31,12,,,,,1.6,1.1,1.2*37
$GPGSV,3,1,12,12,79,068,31,30,63,254,43,14,50,271,41,05,43,076,*79
$GPGSV,3,2,12,09,37,126,36,27,23,126,28,02,16,094,,29,16,192,36*7F
$GPGSV,3,3,12,01,14,324,,31,11,299,29,32,09,333,30,24,07,116,*7F
$GPRMC,164632.000,A,5256.6625,N,00114.4059,W,0.00,,260609,,A*62
$GPGGA,164633.000,5256.6625,N,00114.4059,W,1.08,1.1,75.9,M,47.5,M,,0000*71
$GPGSA,A,3,14,32,27,30,29,09,31,12,,,,,1.6,1.1,1.2*37
$GPRMC,164633.000,A,5256.6625,N,00114.4059,W,0.00,,260609,,A*63
$GPGGA,164634.000,5256.6625,N,00114.4059,W,1.08,1.1,75.9,M,47.5,M,,0000*76
$GPGSA,A,3,14,32,27,30,29,09,31,12,,,,,1.6,1.1,1.2*37
$GPRMC,164634.000,A,5256.6625,N,00114.4059,W,0.00,,260609,,A*64
$GPGGA,164635.0
```

This is a screenshot of the raw output of the GPS module, you can see the output of the NMEA sentences discussed earlier.

Programming

Now that you have a circuit up and running, and if you are already proficient with PICAXE programming you could probably now go off and start using the data from the GPS using only a few simple commands.

But next I will present a simple run through of a program that will demonstrate all you need to know to begin using GPS with PICAXE.

Program

```
*** This program will input the GPS serial data and process***  
*** It using the variables on the PICAXE. The GPS outputs ***  
*** 4800 baud serial data by default, so we will use this ***'
```

Data_in:

```
'Use the qualifier "$GPGGA" to input the GGA NMEA sentence. Use the variable b0 as a  
'dummy for all the characters we don't want NB, including commas'  
serin 0, T4800, ("GPGGA"),b0,b1,b2,b3,b4,b5,b6,b7,b8,b9,b10
```

```
'Flash an LED when a GGA sentence is input'  
toggle 6
```

```
'So now you have the time stored in these variables, you can now use them however you want,  
'store them in EEPROM with the poke command or even display them to a LCD for a very accurate  
'clock down to the millisecond.
```

```
'All I will do with the data is debug in this loop to show the time'  
debug
```

```
goto Data_in
```

Program

The screenshot shows the PICAXE Programming Editor interface. The main window displays a program file named 'gps with picaxe.bas'. The program code includes comments and a loop labeled 'Data_in' that uses the '\$GPGGA' command to read GPS data and outputs it to variables b0 through b13. A 'debug' command is used to display the values of these variables.

```
1  '*** This program Will input the GPS serial data and process***'  
2  '*** It using the varriables on the PICAXE. The GPS outputs ***'  
3  '*** 4800 baud serial data by default, so we will use this ***'  
4  
5  
6  Data_in:  
7  
8  
9  'Use the qualifier "$GPGGA" to input the GGA NMEA sentnece. Use the varriable b  
10 'dummy for all the characters we don't want NB,including commas'  
11 serin 0, T4800, ("GPGGA"),b0,b1,b2,b3,b4,b5,b6,b7,b8,b9,b10  
12  
13 'Flash an LED when a GGA sentence is input'  
14 toggle 6  
15  
16 'So now you have the time stored in these varriables, you can now use them howe  
17 'store them in eeprom with the poke command or even display them to a LCD for a  
18 'clock down to the milisecond.  
19  
20 'All I will do with the data is debug in this loop to show the time'  
21 debug  
22  
23 goto Data_in  
24
```

The 'Debug - (88)' window shows the following output:

outputs	64	\$40	%01000000	'@'
infra/key	0	\$00	%00000000	...
b0	0	\$00	%00000000	...
b1	49	\$31	%00110001	'1'
b2	50	\$32	%00110010	'2'
b3	53	\$35	%00110101	'5'
b4	49	\$31	%00110001	'1'
b5	50	\$32	%00110010	'2'
b6	52	\$34	%00110100	'4'
b7	46	\$2E	%00101110	'.'
b8	48	\$30	%00110000	'0'
b9	48	\$30	%00110000	'0'
b10	48	\$30	%00110000	'0'
b11	0	\$00	%00000000	...
b12	0	\$00	%00000000	...
b13	0	\$00	%00000000	...

The debug output shows a timestamp of 12:51:24.000. The 'Clock 2' window shows the local UK time as 12:51. A red box highlights the '12:51' in the clock display.

Working nicely

Internet time is actually slow by 9 seconds!

The screenshot shows a Windows desktop with a calendar for July 2009. The local UK time is 13:51:15, while the internet time is 12:51. A red box highlights the '12:51' in the clock display.

Troubleshooting

The EM-410 is a 3.3v device so as a result the serial it outputs is around 3v. If the serial input is connected to a pin which is a Schmitt trigger there will be insufficient voltage to drive it. See the following posts on the PICAXE forum for details:

<http://www.picaxeforum.co.uk/showthread.php?t=11711>

<http://www.picaxeforum.co.uk/showthread.php?t=8609>

Update: There is now a fix for this using a logic level shifter, see application note 1

4800 baud rate is not supported fully across the PICAXE range, read the “serin” section of the Basic commands PICAXE manual.

I recommend using an external resonator on the PICAXE for increased reliability.

As with any project make sure you read all relevant documentation if you want to use any other hardware as to not cause damage t your electronics.

If all else fails.... Just set up exactly as my example using the same pins and go from there. My full PICAXE schematic can be found at the end.

Conclusion

So there you have a simple introduction into interfacing any serial GPS module to a PICAXE microcontroller.

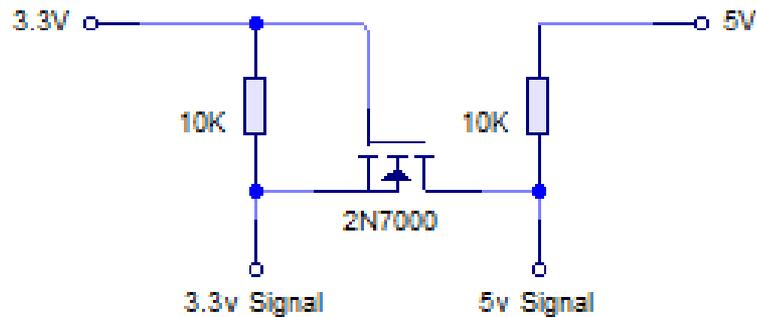
Once you are able to extract data freely, you can move onto more advanced operations. Using the longitude and latitude you could calculate bearings or you could send the coordinates to a computer and write a short C program which will interface with something like Google Earth, there are probably many discussions of such projects online. Hope this helps.

Application note 1

This is a solution to the problem of insufficient voltage levels to trigger a Schmitt Trigger pin on a PICAXE when using the “serin” command. The solution is a DC voltage level shifter.

A level shifter will change the voltage level according to the circuits’ power lines. E.g. for us the level shifter will change between 3.3v and 5v. Also its bi-directional.

It’s a very simple set up that uses any old MOSFET and two resistors.



I used the general purpose 2N7000 MOSFET, but I had used some 3A power MOSFET’s while I was waiting for the 2N7000’s to arrive!

The Gate is always connected to the LOWER voltage.

PICAXE Setup

Using a PICAXE 18X with the EM-410 (should also work for EM-406)

